

SCHEME OF VALUATION

(Scoring Indicators)

Revision: DESIGN OF MACHINE ELEMENTS		Course Code: 5021		
Qst.No.	Scoring Indicator	Split Up	Sub total	Total
PART A				
I 1)	<p><u>Pitch</u> - it is the distance from one point on a screw thread to the corresponding point of the adjacent screw thread measured parallel to the axis of the screw</p> <p><u>Lead</u> - it is the distance moved by the threaded part parallel to the axis of screw in one complete turn.</p>	1	2	
2)	$w = d/4, t = \frac{2}{3}w = \frac{d}{6}, l = 1.5d$ where $d$ = diameter of the shaft in mm $w$ = width of the key in mm $t$ = thickness of height of the key in mm $l$ = length of the key in mm.	2	2	
3.	$\frac{T}{J} = \frac{\tau}{r} = \frac{G\theta}{l}$	2	2	
4.	if a governor is too sensitive, it may fluctuate continuously above and below the mean speed because when the lead on the engine falls or increases. The process is hunting.	2	2	
5	1) no slip takes place, hence perfect velocity ratio occurs. 2) more compact than belt drive. 3) it can be used when exact timing in movement is desired. 4) Unaffected by environmental conditions. 5) it is more durable. 6) no initial tension is required.	2	2	
				5x2 = 10

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	<b>PART-B</b>			
II	<p>1) a) type of load and stresses caused by the load  b) motion of the part  c) selection of material  d) Form and size of the parts  e) Frictional resistance and lubrication  f) Convenient and economical features  g) Use of standard parts  h) Safety of operation  i) Workshop facility  j) Number of machines to be manufactured  k) cost of construction  l) Assembling  m) Durability and reliability  n) Effect of environment</p> <p>2) The efficiency of a screw jack = <math>\frac{\text{ideal effort}}{\text{Actual effort}}</math>  Effort required to lift the load when considering screw friction } <math>P = w \tan(\alpha + \phi)</math>  when neglecting friction, <math>P_0 = w \tan \alpha</math>  Hence <math>\eta = \frac{P_0}{P} = \frac{w \tan \alpha}{w \tan(\alpha + \phi)}</math>  <math>\eta = \frac{\tan \alpha}{\tan(\alpha + \phi)}</math>  This equation shows that the efficiency of a screw jack is independent of the load raised.</p>		6	6
			6	

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3)	<p> <math>d_o = 200 \text{ mm}, d_i = 150 \text{ mm}</math>  <math>\tau = 60 \text{ MPa} = 60 \text{ N/mm}^2</math>                      Diameter ratio, <math>k = \frac{d_i}{d_o} = \frac{150}{200} = 0.75</math>                      strength of the shaft means the maximum torque that can be transmitted.                      then, <math>T = \frac{\pi}{16} \tau d_o^3 (1 - k^4)</math>  <math>= \frac{\pi}{16} \times 60 \times 200^3 (1 - 0.75^4)</math>  <math>= 64427193.09 \text{ N-mm}</math>  <math>= 64.43 \text{ KN-m}</math> </p>		6	
4)	<p>                     sketch-4 }                      label-2 } 6                 </p>			

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5	<p>9 Displacement diagram when the follower moves with uniform velocity.</p> <p>7.10 Displacement diagram when the follower moves with SHM</p> <p>Displacement diagram when the follower moves with uniform acceleration and retardation</p>			
			2 2 2	6

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6) The turning moment diagram developed by a single cylinder four stroke internal combustion engine for one complete cycle is shown in Fig 8.6.

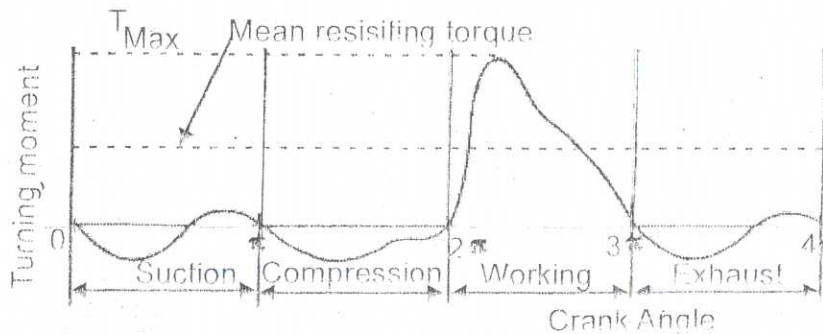


Fig-4)  
mk-2/6

Fig 8.6 Turning moment diagram

We know that in a four stroke internal combustion engine, there is only one power stroke after the crank has turned through two revolutions (i.e.,  $720^\circ$  or  $4\pi$  radians) or one cycle. Since the product of the turning moment and the angle turned is the work done, therefore, the area of turning moment diagram represents the work done per cycle. If the speed is same after one cycle then work done by the engine is equal to the resistance overcome during this time. The total area of the turning moment diagram will, therefore, be equal to the area of resistance diagram. Generally, resistance is assumed to be constant throughout the cycle. This mean resistance torque is determined by dividing the area of turning moment diagram by the angle turned in one cycle. The mean resistance torque as shown by a horizontal line.

7. Advantages -

- 1) They give positive drive and constant speed ratio.
- 2) more compact due to shorter center distance
- 3) can be operated at higher speeds.
- 4) Used where precise timing is desired
- 5) wide range of gear transmitted
- 6) can be used for non intersecting and non parallel shaft.

Dis Advantages

- 1) Not suitable for large center distance
- 2) Requires perfect alignment of shafts.
- 3) Lubrication is required.
- 4) Manufacturing of gears is complex.
- 5) Error in manufacturing of gears causes vibrations and noise.

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Qst.No.	Scoring Indicator	Split Up	Sub total	Total
	<p>PART - C</p> <p>UNIT - 1</p>			
III a)	<p>Sunk key - Rectangular sunk key</p> <ul style="list-style-type: none"> <li>- Square sunk key</li> <li>- Parallel sunk key</li> <li>- Gib headed key</li> <li>- Feather key</li> <li>- Woodruff key.</li> </ul> <p>Saddle key - Hollow saddle key</p> <ul style="list-style-type: none"> <li>- Flat saddle key</li> </ul> <p>Tangent key</p> <p>Round key</p> <p>splines.</p>	3	7	
b)	<p><math>D = 0.4 \text{ m}</math>, <math>P = 1.1 \text{ MPa}</math>, <math>\sigma_t = 32 \text{ MPa}</math>, <math>n = 12</math></p> <p>The force acting on the cylinder head, <math>P = \frac{\pi}{4} D^2 p</math></p> $= \frac{\pi}{4} \times (0.4 \times 10^3)^2 \times 1.1$ <p>Resistance offered by the bolts, <math>P = \frac{\pi}{4} d_c^2 \sigma_t n</math></p> $= \frac{\pi}{4} \times d_c^2 \times 32 \times 12$ <p>Equating the above two equations</p> $\frac{\pi}{4} d_c^2 \times 32 \times 12 = \frac{\pi}{4} (0.4 \times 10^3)^2 \times 1.1$ $d_c = \sqrt{\frac{(0.4 \times 10^3)^2 \times 1.1}{32 \times 12}} = 21.41 \text{ mm}$ <p>Nominal diameter, <math>d = \frac{d_c}{0.84} = \frac{21.41}{0.84} = 25.49 \text{ mm}</math></p> <p style="text-align: center;">say <u>28 mm</u></p>	2	8	2



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	<p>using the relation, <math>T = P' h = P \times \frac{d_m}{2}</math>  <math>\therefore</math> Effort applied at the end of the lever          is by the lever, <math>P' = \frac{P d_m}{2L}</math>  <math>= \frac{3945.59 \times 40}{2 \times 450} = \underline{\underline{175.35 N}}</math></p> <p style="text-align: center;"><u>UNIT - II</u></p> <p>Va) <math>d_o = d_o = 200 \text{ mm}</math>, <math>d_i = 150 \text{ mm}</math>  <math>\tau_s = 50 \text{ MPa} = 50 \text{ N/mm}^2</math>  <math>k = \frac{d_i}{d_o} = \frac{150}{200} = 0.75</math></p> <p>Strength means the maximum torque that can be transmitted</p> $T = \frac{\pi}{16} \tau d_o^3 (1 - k^4)$ $= \frac{\pi}{16} \times 50 \times 200^3 (1 - 0.75^4)$ $= 53689327.58 \text{ N-mm}$ $= \underline{\underline{53.68 \text{ KN-m}}}$	3	8	8
	<p>Strength means the maximum torque that can be transmitted</p> $T = \frac{\pi}{16} \tau d_o^3 (1 - k^4)$ $= \frac{\pi}{16} \times 50 \times 200^3 (1 - 0.75^4)$ $= 53689327.58 \text{ N-mm}$ $= \underline{\underline{53.68 \text{ KN-m}}}$	2	7	7
	<p>b) Design of shaft          Determine the mean torque, <math>T_{\text{mean}} = \frac{60P}{2\pi n}</math>          compute the maximum torque as per the given conditions          if <math>T_{\text{max}}</math> is <math>x\%</math> greater than <math>T_{\text{mean}}</math>, then  <math>T_{\text{max}} = (100 + x)\%</math> of <math>T_{\text{mean}}</math>          if the condition is not specified then <math>T_{\text{max}} = T_{\text{mean}}</math></p>	3	2	2



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	OR			
V1a)	$P = 105 \text{ kW} = 105 \times 10^3 \text{ N} \cdot \text{m/s}, \quad N = 160 \text{ rpm}$ $\tau = 65 \text{ MPa}, \quad l = 3.5 \text{ m} = 3.5 \times 10^3 \text{ mm}$ $\theta = 1^\circ, \quad G = 80 \times 10^3 \text{ N/mm}^2$ $T = \frac{60P}{2\pi N} = \frac{60 \times 105 \times 10^3}{2\pi \times 160} = 6266.73 \text{ N}\cdot\text{m}$ $= 6266.73 \times 10^3 \text{ N}\cdot\text{mm}$ <p>considering strength,</p> $T = \frac{\pi}{16} \tau d^3$ $d = \sqrt[3]{\frac{16 \times 6266.73 \times 10^3}{\pi \times 65}} = 78.89 \text{ mm}$ <p>considering torsional rigidity</p> <p>Using rigidity equation, <math>\theta = \frac{584 T l}{G d^4}</math></p> $d = \sqrt[4]{\frac{584 \times 6266.73 \times 10^3 \times 3.5 \times 10^3}{80 \times 10^3 \times 1}}$ $= 112.49 \text{ mm}$ <p>Take the largest value, <math>d = 112.49</math> say <u>120 mm</u></p>		2	
			2	7
b)	<p>strength eqn. for hollow shaft, <math>\tau_H = \frac{\pi}{16} \tau d_o^3 (1-k^4)</math></p> <p>for solid shaft, <math>\tau_s = \frac{\pi}{16} \tau d^3</math></p> $\therefore \frac{\tau_H}{\tau_s} = \frac{\frac{\pi}{16} \tau d_o^3 (1-k^4)}{\frac{\pi}{16} \tau d^3} = \frac{d_o^3 (1-k^4)}{d^3} \quad -0$		3	

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	<p>Let weight of hollow shaft, <math>w_H =</math> weight of solid shaft <math>w_S</math>.</p> $A_H \times l_H \times \rho_H = A_S \times l_S \times \rho_S$ $A_H = A_S \quad l_H = l_S, \rho_H = \rho_S$ $\frac{\pi}{4} (d_o^2 - d_i^2) = \frac{\pi}{4} d^2$ $d_o^2 - d_i^2 = d^2$ $d_o^2 (1 - (\frac{d_i}{d_o})^2) = d^2$ $d_o^2 (1 - k^2) = d^2$ $d = \sqrt{d_o^2 (1 - k^2)} = d_o \sqrt{1 - k^2} \quad \text{--- (1)}$ <p>Combining (1) &amp; (2)</p> $\frac{T_H}{l_S} = \frac{d_o^3 (1 - k^4)}{(d_o \sqrt{1 - k^2})^3} = \frac{d_o^3 (1 - k^2)(1 + k^2)}{d_o^3 (1 - k^2) \sqrt{1 - k^2}}$ $\frac{T_H}{l_S} = \frac{1 + k^2}{\sqrt{1 - k^2}}$ <p>Since <math>k</math> is less than 1, suppose <math>k = 0.5</math> then</p> $\frac{T_H}{l_S} = \frac{1 + 0.5^2}{\sqrt{1 - 0.5^2}} = 1.44$ $\frac{T_H}{l_S} > 1 \quad \text{or} \quad T_H > T_S$ <p>This shows that torque transmitted by the hollow shaft is greater than that of the solid shaft.</p>			

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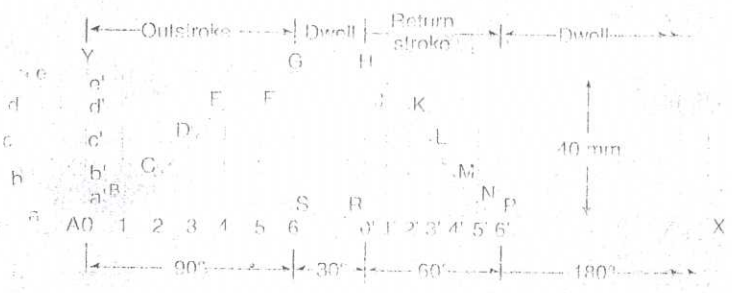
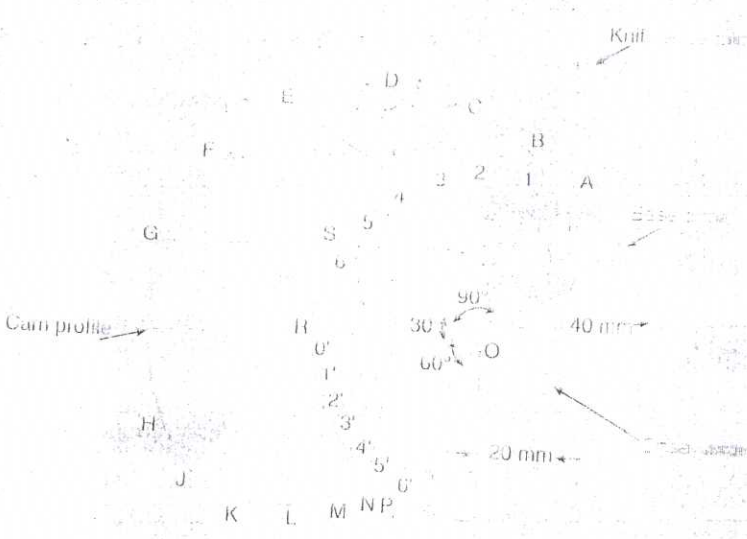
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VII a)	<p style="text-align: center;"><u>UNIT - III</u></p>			7
b)	<p> <math>d = 65 \text{ mm} = 65 \times 10^{-3} \text{ m}</math>, <math>W = 5 \times 10^3 \text{ N}</math>  <math>N = 200 \text{ rpm}</math>, <math>\rho/d = 3</math>, <math>\mu = 0.02</math>  <math>l = 3d = 3 \times 65 = 195 \text{ mm}</math>                      Projected area, <math>A = l \cdot d = 195 \times 65 = 12675 \text{ mm}^2</math>  <math>P_b = \frac{W}{A} = \frac{5 \times 10^3}{12675} = 0.39 \text{ N/mm}^2</math>  <math>V = \frac{\pi d N}{60} = \frac{\pi \times 65 \times 10^{-3} \times 200}{60} = 0.68 \text{ m/s}</math>  <math>Q_g = \mu W V = 0.02 \times 5 \times 10^3 \times 0.68</math>  <math>= 68 \text{ W or J/s}</math> </p>	4	2	8
			2	

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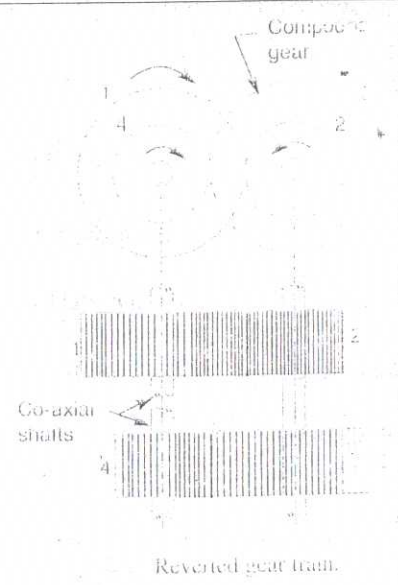
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VIII a)	OR. i) Depending upon the directions of load to be supported a) Radial bearing b) Thrust bearing	2	7	7
	ii) Depending upon the nature of contact a) sliding contact bearing b) Rolling contact bearing (Borent note)	2 3		
b)		3		
		5	4	

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	UNIT - IV				
IX a)	<p>When the axes of the first gear (driver) and the last gear (driven) are co-axial then the gear train is known as reverted gear train.</p>  <p style="text-align: right;">Fig-4 note-1</p>			7	
	<p>Applications - Automotive transmissions, lathes back gears, clocks etc.</p>	-	2		
b)	<p> <math>d = 600 \text{ mm} = 0.6 \text{ m}</math>, <math>N = 200 \text{ rpm}</math>  <math>\mu = 0.25</math>, <math>\theta = 160^\circ = 160 \times \frac{\pi}{180} = 2.79 \text{ rad}</math>  <math display="block">v = \frac{\pi d N}{60} = \frac{\pi \times 0.6 \times 200}{60} = 6.283 \text{ m/s}</math> <math display="block">\frac{T_1}{T_2} = e^{\mu \theta} = e^{0.25 \times 2.79} = 2.01</math> <p>Power transmitted <math>P = T_1 \left(1 - \frac{1}{e^{\mu \theta}}\right) \cdot v</math></p> <math display="block">= 25 \left(1 - \frac{1}{2.01}\right) \times 6.283</math> <math display="block">= 7.893 \text{ kW}</math> </p>		2	2	8
			4		

Scheme of Valuation

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Xa)	<p style="text-align: center;">OR</p> <p>Due to the insufficient frictional grip between the belt and its pulley sometimes the driving pulley moves without carrying the belt with it. The relative motion between the pulley and the belt is called the slip of the belt.</p> <p>When the belt passes from the slack side to the tight side, a certain portion of the belt extends and it contracts again when the belt passes from the tight side to slack side. Due to these changes of length, there is a relative motion between the belt and the pulley surface. This relative motion is termed as creep.</p>			7
b)	<p><math>d_1 = 300 \text{ mm}, N_1 = 200 \text{ rpm}, C = 3 \times 10^3 \text{ mm}</math>  <math>N_2 = 120 \text{ rpm}, t = 5 \text{ mm}, S = S_1 + S_2 = 6\%</math></p> $\frac{N_2}{N_1} = \frac{d_1 + t}{d_2 + t} \left(1 - \frac{S}{100}\right)$ $d_2 = \left[ (d_1 + t) \left(1 - \frac{S}{100}\right) \times \frac{N_1}{N_2} \right] - t$ $= \left[ (300 + 5) \left(1 - \frac{6}{100}\right) \times \frac{200}{120} \right] - 5$ $= 472.93 \text{ mm}$ $L_0 = \frac{\pi}{2} (d_2 + d_1) + 2C + \frac{(d_2 - d_1)^2}{4C}$ $= \frac{\pi}{2} (472.93 + 300) + 2 \times 3 \times 10^3 + \frac{(472.93 - 300)^2}{4 \times 3 \times 10^3}$ $= 7216.45 \text{ mm} = 7.22 \text{ m}$		4	8